

Heat transfer enhancement by the suppression of the stratified stagnant core in a rectangular differentially heated cavity

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¹ Heat transfer enhancement by the suppression of the stratified

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stagnant core in a rectangular differentially heated cavity

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10 Abstract

This work investigates numerically a natural convection flow in a rectangular differentially 11 heated cavity. The aspect ratio of the cavity (height over width) is 4, the working fluid is air 12 and the Rayleigh number based on the height of the cavity is 9×10^7 . A large rectangular 13 obstacle is placed in the center of the cavity. The influence of the size of that obstacle 14 and the effect of a new geometry (obtained by extrusion of two rectangular forms from the 15 obstacle) on the flow dynamics and heat transfers are investigated. The global and local heat 16 transfers modifications, compared to the case without obstacle, are highlighted for several 17 configurations. In such a flow regime, an optimal geometry and a solid-to-fluid conductivity 18 ratio are determined. This geometry leads, for an adiabatic obstacle, to a global heat transfer 19 increase of 4.39% with a local heat transfer increase up to 80%. 20

²¹ Keywords: Differentially-Heated Cavity, Natural Convection, Heat Transfer Modification

22 1. Introduction

In the past decades, rectangular differentially-heated cavities (DHC) have been widely 23 studied experimentally and numerically for laminar, transient and turbulent flows [1-6]. 24 Natural convection in a rectangular DHC is known to have a lot of industrial and engineer-25 ing applications as solar collectors [7], cooling of electronic systems [8], air-conditioning [9], 26 double pane windows, and others. However, the size, performance and effectiveness of those 27 engineering systems are often limited by the ability to transfer heat to or from the system. 28 Thus, working toward an energy-efficient society, it is fundamental to understand and con-29 trol the attendant phenomena to increase or reduce the associated heat transfers [10, 11]. 30 To manipulate heat transfer in a rectangular DHC, both passive and active perturbation 31 strategies of the flow were investigated. The studies showed that active actuators, located at 32 the isothermal wall to modify the thermal or velocity fields, can be either mechanical [12] or 33 thermal [13–15]. In every cases, the main goal is to excite instability waves inside the boundary layer (e.g. Tollmien-Schlichting waves) or inside the core region (e.g. gravity waves), in 35 order to observe a significant increase of temperature gradients at the wall [16]. A numerical investigation (2D-DNS) for a cavity of aspect ratio four was carried out by Chorin et al. [14] 37 using a thermal actuator located at the hot wall. They found that a thermal perturbation 38 has a significant impact on heat transfer up to 16% downstream the disturbed area and up 39

to 2% on the cold wall. Recently, Thiers et al. [15] have shown optimal positions of two
local thermal disturbances, one per isothermal wall: the optimum height of the actuator at
the hot wall is 70% of the hot plate height and at 30% of the cold plate height. At those
positions, the increase of heat transfer reached 5.5% by synchronised square waves.

On the other hand, in general, passive actuators are mechanical. They can be located 44 at the wall or away from it. If we consider techniques applied to the wall, parameters 45 that can influence heat transfer at the isothermal walls are the roughness [17, 18] or a 46 modification of the surface by adiabatic or conducting fins [19–21]. For a two-dimensional 47 differentially heated rough square cavity, effects of frequency and dimensionless amplitude 48 of sinusoidal roughness elements on the hot, and both the hot and cold walls simultaneously, 49 have been investigated numerically by Yousaf and Usman [18] using a single relaxation time 50 Bhatnagr-Gross and Krook (BGK) model in a Lattice Boltzmann method (LBM). The 51 range of Rayleigh numbers explored was $Ra \in [10^3; 10^6]$ and a Newtonian fluid of Prandtl 52 number equals to 1.0 was considered. For all studied cases, a reduction in the overall Nusselt 53 number was noted, up to 17%. The unsteady natural convection flow adjacent to the finned 54 sidewall of a differentially heated cavity has been studied by Xu et al. [22]. In particular, a 55 comparison between cases with a conducting fin and with an adiabatic fin was carried out. 56 The results show that the fin may significantly influence natural convection in the cavity 57 and even trigger the transition to unsteady natural convection in the cavity. Indeed, the 58 authors found that the conducting fin improves the transient convective flows in the cavity 59 and enhances heat transfer across the cavity (by up to 52% in comparison with the case 60 without a fin). Recently, Chorin et al. [23] studied experimentally, a natural convection flow 61 in a rectangular DHC disturbed by introducing a localized obstacle which acts as a small 62 spatial extent passive system. The obstacle is placed inside the hot boundary layer. The 63 influence of the length and the vertical location for an insulating and a conducting obstacle 64 have been analysed. A relative heat transfer increase up to 83% is observed downstream the 65 insulating obstacle for the largest length and highest vertical location. 66

Another way of altering the natural convection flow and heat transfer is to locate a 67 solid obstacle somewhere in the DHC. Obviously, the size, number, position and physical properties of solid obstacles have deep influences on the enclosed fluid flow and heat transfer 69 structures. A literature review reveals the existence of a large number of numerical studies 70 only devoted to natural convection phenomenon occurring in square DHC containing solid 71 bodies with different thermal behaviours: including heat generation [24, 25], adiabatic [26–28] 72 and conducting properties [29, 30]. In particular, for $Ra \in [10^3; 10^6]$ and Pr = 0.071, 0.71 and 73 7.1, Bhave et al. [27] reported the existence of an optimum size of the adiabatic solid which 74 allows a maximum of heat transfer, for each Ra. Authors also added correlations, predicting 75 optimum solid sizes, and the corresponding maximum heat transfer as a function of RaPr. 76 Karki et al. [31] also confirmed the existence of an optimum size of the adiabatic solid. 77 These authors underlined that heat transfer across the cavity decreases by splitting the solid 78 into two or four fragments, but outside of the zone where conduction dominates. In practice, 79

such solids are not exactly adiabatic bodies: they only have a low thermal conductivity. 80 Thus, the Rayleigh number is not enough. The solid-to-fluid thermal conductivity ratio 81 and the number of solids have to be considered in a square differentially heated cavities 82 with conducting solids. In an earlier paper, House et al. [32] numerically showed that heat 83 transfer across a differentially heated cavity may be enhanced (reduced) by the addition of 84 a single solid with a solid-to-fluid thermal conductivity ratio smaller (greater) than unity. 85 They also concluded that heat transfer may reach a minimum as the solid size was increased 86 for large solid-to-fluid conductivity ratios. The results published by Zhao et al. [33] confirm 87 the heat transfer enhancing with a weakly conductive solid inside a differentially heated cavity for a moderate solid-to-fluid volume ratio. 89

In conclusion, this review of the literature shows that few publications deal with the in-90 fluence on heat transfer of a solid located in the core region of a rectangular cavity. However, 91 in a rectangular DHC, there is also a stratified stagnant core of fluid that does not partici-92 pate in the convection heat transfer between the isothermal walls. If this stagnant region is 93 completely replaced by a centrally-placed adiabatic obstacle, a corresponding steady-state 94 heat transfer enhancement could also be observed. Thus, the main objective of this work is 95 to study numerically the impact of a solid obstacle on the heat transfer, in DHC of vertical 96 aspect ratio equal to 4, when the flow is two-dimensional and laminar ($\operatorname{Ra}_H = 9 \times 10^7$). In particular, the influence of the geometry of the solid obstacle is investigated in detail. The 98 present article is organized as follows: in Sec. 2 the problem studied, its modelling as well 99 as a summary of the numerical methods used are presented. In Sec. 3 the numerical results 100 obtained are exhibited for some relevant situations. Flow fields, thermal fields and the heat 101 transfer behaviour are presented and analyzed. 102

¹⁰³ 2. Problem and mathematical model

104 2.1. Problem definition

Consider a two-dimensional vertical differentially heated cavity of height H and width W, 105 filled with air, assumed to be a Newtonian fluid, of kinematic viscosity ν , thermal diffusivity 106 α , thermal conductivity k_f , thermal expansion β and density ρ . The Prandtl number $\Pr = \frac{\nu}{\alpha}$ 107 is supposed to be constant and equal to 0.71. The cavity aspect ratio $A_z = \frac{H}{W}$ is set to 4. 108 The two opposite vertical walls of the cavity (x-direction) are maintained isothermal: T_{hot} 109 at x = 0 and T_{cold} at $x = \frac{W}{H} = \frac{1}{4}$ with $T_{hot} > T_{cold}$. The top and bottom walls of the cavity 110 are adiabatic. The gravitational acceleration \vec{q} acts in negative z-direction. Three cases are 111 considered: case 1 is the rectangular DHC without solid, only filled with the working fluid 112 (see Fig. 1a); case 2 is the rectangular DHC with an adiabatic or conductive rectangular 113 solid placed at the center of the cavity (see Fig. 1b); finally, case 3 is the rectangular DHC 114 with an adiabatic or conductive extruded solid placed at the center of the cavity (see Fig. 115 1c). 116



Fig. 1. Schematic of three configurations studied: a) Base case; b) Rectangular case; c) Extruded case.

117 2.2. Mathematical model

Heat and fluid flows can be described by the unsteady two-dimensional Navier-Stokes 118 equations under the Oberbeck-Boussinesq hypothesis. The Oberbeck-Boussinesq approxi-119 mation ignores all density variations of the fluid in governing equations, except when asso-120 ciated with the gravitational term. Using the temperature difference $\Delta T = T_{hot} - T_{cold}$ and 121 the mean temperature $T_{mean} = \frac{T_{hot} - T_{cold}}{2}$, the reduced temperature θ can then be defined as 122 $\theta = \frac{T - T_{mean}}{\Delta T}$. Using the cavity height H as the reference length and the Rayleigh number 123 based on this cavity height $Ra = g\beta\Delta T H^3/(\nu\alpha)$, the reference velocity can be defined as 124 $u_{ref} = \alpha \mathrm{Ra}^{1/2}/H$, the convection time as $t_{ref} = H^2 \mathrm{Ra}^{-1/2}/\alpha$ and the reference pressure as 125 $P_{ref} = \rho u_{ref}^2$. The dimensionless form of the two-dimensional Navier-Stokes equations under 126 the Oberbeck-Boussinesq hypothesis yields: 127

$$\begin{cases} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0\\ \frac{\partial u}{\partial t} + u\frac{\partial u}{\partial x} + w\frac{\partial u}{\partial z} = -\frac{\partial p}{\partial x} + \frac{\Pr}{\operatorname{Ra}^{0.5}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial z^2}\right)\\ \frac{\partial w}{\partial t} + u\frac{\partial w}{\partial x} + w\frac{\partial w}{\partial z} = -\frac{\partial p}{\partial z} + \frac{\Pr}{\operatorname{Ra}^{0.5}} \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial z^2}\right) + \Pr\theta\\ \frac{\partial \theta}{\partial t} + u\frac{\partial \theta}{\partial x} + w\frac{\partial \theta}{\partial z} = \frac{1}{\operatorname{Ra}^{0.5}} \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial z^2}\right) \end{cases}$$
(1)

where u is the non-dimensional x-direction velocity component, w is the non-dimensional z-direction velocity component, p the non-dimensional pressure.

¹³⁰ Within the solid obstacle, the heat equation is expressed as:

$$\frac{\partial\theta}{\partial t} = a_s \left(\frac{\partial^2\theta}{\partial x^2} + \frac{\partial^2\theta}{\partial z^2} \right) \tag{2}$$

where a_s is the thermal diffusivity of the solid obstacle.

132 2.3. Boundary conditions

Non-slip boundary conditions are imposed on the solid walls of the cavity and the solidobstacle, i.e.

$$u = w = 0. (3)$$

Horizontal walls of the enclosure are assumed to be perfectly adiabatic. Thus, boundary
 conditions for temperature are expressed as:

$$\left. \frac{\partial \theta}{\partial z} \right|_{(x,z=0)} = \left. \frac{\partial \theta}{\partial z} \right|_{(x,z=1)} = 0.$$
(4)

¹³⁷ The thermal boundary conditions of the vertical cavity-walls are given by:

$$\theta(x=0,z) = 0.5, \qquad \theta(x=W/H=0.25,z) = -0.5.$$
 (5)

The conservation of the heat flux at the solid obstacle–fluid interfaces could be expressed as following,

$$\left. \frac{\partial \theta}{\partial n} \right|_{fluid} = k_r \left. \frac{\partial \theta}{\partial n} \right|_{solid},\tag{6}$$

where *n* is a vector normal to solid surface pointing outwards and k_r is the solid-to-fluid-ratio of thermal conductivity: $k_r = k_s/k_f$. Four specific values of k_r are considered in the last section 3.3: $k_r = 0$ for the perfectly adiabatic solid ($k_s = 0$), $k_r = 10^{-3}$ (low k_s), $k_r = 1$ (air-like k_s), and $k_r = 10^2$ (high k_s).

¹⁴⁴ 2.4. Convective transport evaluation and flow visualization

The fluid flows in the DHC are visualized using the Line Integral Convolution (LIC). It was first proposed by Cabral and Leedom [34]. For each grid point in a vector field, a one-dimensional low-pass filter kernel function is used to convolve the noise texture so that it is bidirectionally symmetrical, thereby providing an output texture value. Thus, LIC could characterize flow fields more compactly and comprehensively than geometric visualization methods such as pathlines [35].

To estimate the impact of the obstacles on heat transfer at isothermal walls, the averaged Nusselt number at the hot wall can also be calculated as follows:

$$\langle \mathrm{Nu} \rangle_{x=0} = \int_0^1 -\frac{\partial \theta}{\partial x} \Big|_{x=0} dz ,$$
 (7)

The same expression without the minus sign and evaluated at x = W/H is applied at the cold wall. Due to the energy conservation across the enclosure, the average Nusselt numbers at the hot and cold walls must be equal, that is, $\langle Nu \rangle_{x=0} = \langle Nu \rangle_{x=W/H}$. In order to compare heat transfer with or without an obstacle, the following parameter is defined:

$$\langle G_{\rm Nu} \rangle = \frac{\langle {\rm Nu} \rangle_{x=0} - \langle {\rm Nu} \rangle_{\rm bf}}{\langle {\rm Nu} \rangle_{\rm bf}} \times 100$$
(8)

where $\langle Nu \rangle_{bf}$ denotes the corresponding value of the Nusselt number for the base flow (bf), that is to say without solid. Thus G_{Nu} represents the relative gain ($G_{Nu} > 0$) or loss ($G_{Nu} < 0$) of heat transfer compared to the case without modifications ($G_{Nu} = 0$) when ¹⁶⁰ a solid obstacle is located at the cavity center (see Fig. 1). In the same way, the height-¹⁶¹ dependent relative gain $G_{\text{Nu}}(z)$ is defined:

$$G_{\rm Nu}(z) = \frac{{\rm Nu}(z) - {\rm Nu}_{\rm bf}(z)}{{\rm Nu}_{\rm bf}(z)} \times 100$$
(9)

162 2.5. Numerical Methods

The system of equations (1) is solved by the computational fluid dynamics open-source 163 program Nek5000 developed and maintained by Fischer et al. [36] at the Argonne National 164 Laboratory. Nek5000 is a Navier-Stokes solver, which uses a spectral element method pro-165 posed by Patera [37], to accurately resolve the velocity field $\vec{u}(x, z, t)$ and temperature field 166 $\theta(x, z, t)$. This method combines the benefits of high-order spectral methods with finite ele-167 ment methods. The computational domain is made of $N_x \times N_z$ rectangular spectral elements, 168 in the x and z-directions, respectively. The spatial resolution is selected using as a guideline, 169 the mesh reported by [15]. In Figure 2, four examples of meshes are presented. For the 170 adiabatic cases, only the flow domain needs a mesh (see Fig. 2a-b) whereas for conductive 171 obstacles a mesh inside the solid is needed to calculate the temperature field (see Fig. 2c-d). 172 For the thinnest case $(W_1 \rightarrow 0, \text{ see Fig. 2d})$ only one point is considered; that is to say for 173 example, from $z \in [0.7; 0.95]$ (or $z \in [0.05; 0.3]$) the obstacle is only a boundary. 174



Fig. 2. For $H_0 = 0.05$ and $W_0 = 0.04$, four examples of meshes with $N_x \times N_z = 7 \times 21$: a) an adiabatic rectangular obstacle; b) an adiabatic extruded obstacle ($W_1 = 0.08$, $H_1 = 0.1$); c) a conductive extruded obstacle ($W_1 = 0.02$, $H_1 = 0.3$); d) thinnest conductive extruded obstacle ($W_1 \rightarrow 0$, $H_1 = 0.3$).

On each spectral element, the Navier-Stokes equations (see Eq. 1) are rewritten in the weak formulation and discretized by a Galerkin method, where test and trial functions are ¹⁷⁷ sought in different polynomial spaces. Indeed, a $\mathbb{P}_N - \mathbb{P}_{N-2}$ formulation is used: the velocity ¹⁷⁸ and temperature fields are discretized using Nth degree Lagrange interpolants, defined on ¹⁷⁹ the Gauss-Lobatto-Legendre (GLL) quadrature points, as basis and trial functions, while ¹⁸⁰ the pressure field is discretized using Lagrange interpolants of degree N - 2 defined on ¹⁸¹ the Gauss-Legendre quadrature points. The time-derivative terms are discretized by the ¹⁸² third-order backward differentiation formula (BDF3). The nonlinear convective terms are ¹⁸³ computed explicitly using a third-order extrapolation scheme (EXT3), while the linear terms ¹⁸⁴ are treated implicitly. This high-order splitting method (BDF3-EXT3) leads to a Poisson ¹⁸⁵ equation for pressure and Helmholtz equations for temperature and velocity components ¹⁸⁶ that are solved using a generalized minimal residual method (GMRES) where the tolerance ¹⁸⁷ is set to 10⁻⁸. More details on the numerical scheme and appropriate grid resolution can be ¹⁸⁶ found in Deville et al. [38].

189 2.6. Mesh convergence and code validation

The numerical method is validated, comparing our results for the base case (see Fig. 1a) 190 with those reported by Gadoin et al. [39] on a wider range of Rayleigh numbers, between 191 $Ra_H = 6.4 \times 10^6$ and 1.92×10^8 . A mesh with 6×20 spectral elements and a grid polynomial 192 order N = 24 resulting in 144×480 grid points is chosen. For different Rayleigh numbers, 193 averaged Nusselt numbers at the isothermal wall $\langle Nu \rangle$ are reported in Table 1. It can be 194 seen that the present results match very well those reported by Gadoin et al. [39] and that 195 the following correlation $\langle \overline{\text{Nu}} \rangle = 0.311 \times \text{Ra}_{H}^{0.2493}$ is obtained. This relationship is also very 196 close to the numerical correlation $\langle Nu \rangle = 0.29 \text{Ra} H^{0.25}_{H}$ reported by Grondin and Roux [40] 197 and experimental results $\langle Nu \rangle = 0.288 \text{Ra}_{H}^{0.25}$ reported by Belleoud *et al.* [41]. For all other 198 cases (see Figs. 1b and 1c), a mesh convergence study is performed using a p-refinement 199 technique in which the grid polynomial order N was increased: N = 22, 24, 26 and N = 28. 200 It appeared that N = 24 is sufficient to obtain an accurate Nusselt number at the active 201 wall and a sufficiently high resolution of the velocity profile. An increase of the polynomial 202 order does not affect the simulation results. We have also checked that the cold and hot 203 Nusselt numbers are equal. Close to the isothermal walls, the wall-normal distance is smaller 204 than $\frac{(\Delta x)_{min}}{H} = 3.3 \times 10^{-4}$. A constant time-stepping with a target Courant-Friedrichs-Lewy 205 number of 0.5 is used, which is sufficient to guarantee the stability during the simulation. 206

²⁰⁷ Each calculation is extended until the flow reaches a steady stage.

Table 1

Rayleigh	$0.311\times \mathrm{Ra}_{H}^{0.2493}$	Present	Gadoin [39]
$6.4 imes 10^6$	15.47	15.49	15.49
$6.4 imes 10^7$	27.46	27.46	27.46
1.28×10^8	32.65	32.69	32.69
$1.6 imes 10^8$	34.51	34.56	34.56
1.92×10^8	36.12	36.17	36.17

For different Rayleigh numbers, the average Nusselt number at the isothermal wall, $\langle \overline{Nu} \rangle$. Comparison with the numerical results reported by [39] and the correlation $\langle \overline{Nu} \rangle = 0.311 \times \text{Ra}_H^{0.2493}$.

208 2.7. Base flow

The Rayleigh number, $Ra = 9 \times 10^7$, is chosen slightly below the first critical Rayleigh 209 number $Ra_c = 1.052 \times 10^8$ [5]. Thus, the base flow corresponds with a steady state and our 210 results can be compared with those of our previous works [15]. The thickness $\delta_{\theta}(z)$ of the 211 thermal boundary is defined at a given elevation z, as the minimal horizontal distance, from 212 the wall, for which the core temperature is reached [41, 42]. In the same way, the thickness of 213 the dynamic boundary layer $\delta_w(z)$ is defined, at a given elevation z, as the minimal horizontal 214 distance, from the wall, for which the vertical velocity of the fluid vanishes [4]. It can also be 215 observed that the temperature gradients decrease along the hot wall as z increases, whereas 216 the maximum of vertical velocity w increases. In the middle of cavity, z = 0.5, for this 217 Rayleigh number, $\delta_{\theta}(z) = 0.03$ and $\delta_w(z) = 0.05$. 218

219 3. Numerical results and discussion

The primary goal of this work is to find a way to enhance the overall heat transfer in 220 the cavity. A possible way to achieve this goal is to increase the boundary layer velocity at 221 the beginning of the vertical boundary layers by using a solid obstacle. For this purpose, 222 two main configurations are tested. First, a rectangular obstacle is located in the cavity 223 core to suppress the secondary flows. In a second part, the best geometry of the previous 224 configuration is modified by a subsequent extrusion process to generate a new secondary 225 flow by a backward-facing step. In each configuration, the influence of the solid obstacle on 226 the velocity and temperature fields is detailed. Finally, in the third section, effects of heat 227 conduction in the solid obstacle are considered. 228

3.1. Suppression of base secondary flows induced by an adiabatic rectangular obstacle (case
(b) in Fig. 1)

In this section, for forty pairs of (W_0, H_0) , we present in detail the effects of the size of an adiabatic rectangular obstacle (see Fig. 1-b): first on the flow dynamics and in a second part on heat transfer.

234 3.1.1. Flow dynamics

After evaluating the base case, in order to explain the influence of the spacing H_0 between 235 the adiabatic wall and the top or bottom wall of the rectangular obstacle, a steady flow is 236 obtained and the flow visualizations using the LIC-method are shown in Fig. 3. The spacing 237 W_0 between the isotherm wall and the vertical wall of the obstacle is constant: $W_0 = 0.04$. 238 The base case is also presented to show how two recirculation zones are modified by the 239 obstacle: one at $z \approx 0.9$ (see point A) and one at $z \approx 0.8$ (see point B). The same behaviour 240 is observed at the bottom of the cavity due to the centrosymmetry property of the flow (see 241 Fig. 3a). When a rectangular obstacle of height $H_0 = 0.15$ is introduced inside the cavity, 242 the recirculation zone A and B get smaller (see Fig. 3b). If a larger obstacle is inserted 243 $(H_0 = 0.05)$, the two recirculation zones disappear while a small recirculation zone (noted C) 244 is formed at the right of the bottom side (or left of the top side) of the obstacle (see Fig. 3c). 245 This is due to the fact that the velocity inside the vertical channel gets higher than inside 246 the horizontal one $(H_0 > W_0)$; that is to say C corresponds to an hydraulic jump. Finally, 247 if we increase slightly the rectangle height so that $H_0 = 0.03$, as $H_0 < W_0$, the velocity 248 inside the horizontal channel is higher than inside the vertical one. As a consequence, a new 249 recirculation zone is created at the bottom of the vertical left side (or top of the vertical 250 right side) of the obstacle (see Fig. 3d). 251



Fig. 3. Line Integral Convolution (LIC) visualisation for three values of H_0 when $W_0 = 0.04$. The base case is also presented for comparison.

Figure 4 shows vertical velocity profiles at six heights along the hot wall (z = 0.05, z = 0.1, z = 0.5, z = 0.7, z = 0.8 and z = 0.9), for the three cases previously presented ($H_0 = 0.15$, $H_0 = 0.05$, and $H_0 = 0.03$). For $H_0 = 0.15$, as expected, the vertical velocity profiles are close to those of the base case in the lower part of the cavity (see Fig. 4a).

However, in the upper part of the cavity (z = 0.9), the maximum velocity is greater than 256 that of the base case (see Fig. 4b). For smaller values of H_0 , $H_0 = 0.05$ or $H_0 = 0.03$, at the 257 beginning of the boundary layer (z = 0.05 and z = 0.1) it can be observed that the vertical 258 velocity profiles w are higher than those of the base case. As a consequence, in this area, 259 heat transfer is expected to be higher than in the base case. Using the rectangular obstacle, 260 the flow is forced to pass through a vertical channel. It implies that the air flow benefits 261 from a greater exchange length and consequently $G_{\rm Nu}$ should increase. It can be noted that 262 for z = 0.05 and $H_0 = 0.03$, a slight counterflow seen for $x \in [0.03; 0.04]$ corresponds to the 263 C point in Fig. 3d. Finally, it can also be observed for z = 0.5 and 0.7 that vertical velocity 264 profiles are slightly lower than those of the base case; this may be explained because the base 265 flow is naturally concentrated in the mid-section of the cavity due to secondary recirculation 266 (see point B, Fig 3a) or because the three cases studied must overcome frictional resistance 267 from the channel walls.



Fig. 4. Vertical velocity profiles w along the hot wall for six different heights: a) upstream section; b) downstream section. Comparison between the base case and three values of H_0 .

268

In Fig. 5, for $H_0 \in [0.03, 0.25]$ and $W_0 \in [0.03, 0.05]$ (i.e. $W_0 \in [\delta_{\theta}(z = 0.5), \delta_w(z = 0.5)]$ for the base flow case.), the relative mean shear stress at the isothermal wall Γ_T and at the adiabatic wall Γ_Q are presented. They are defined as:

$$\Gamma_T = \left(\frac{\tau}{\tau_{bf}}\right)_{x=\{0;W/H\}}, \quad \Gamma_Q = \left(\frac{\tau}{\tau_{bf}}\right)_{z=\{0;1\}}$$
(10)

where $(\tau)_{x=\{0;W/H\}}$ and $(\tau)_{z=\{0;1\}}$ are, considering a rectangular obstacle at the center, the mean shear stress at isothermal and adiabatic cavity walls respectively. For the base case, the same magnitudes are defined as $(\tau_{bf})_{x=\{0;W/H\}}$ and $(\tau_{bf})_{z=\{0;1\}}$. The values of H_0 for the thickness of the thermal and dynamic boundary layers for base flow case, $\delta_{\theta}(z=0.5)$ and $\delta_w(z=0.5)$, is also superimposed. Clearly, Γ_T and Γ_Q seems to be dependent on H_0 than on W_0 since all curves are almost superimposed (see Figs. 5a and 5b). Moreover, it can be observed in Fig. 5a that $(\tau)_{x=\{0;W/H\}}$ is close to $(\tau_{bf})_{x=\{0;W/H\}}$ as $\Gamma_T \approx 1$. That is to say, the rectangular obstacle does not modify significantly the mean shear stress at the isothermal walls. On the contrary, the influence of the obstacle is more important on the adiabatic walls since $\Gamma_Q \in [0.6; 1.9]$ (see Fig. 5b). One can see that if the vertical aperture $H_0 < \delta_w(z = 0.5)$ a significant increase of $(\tau)_{z=\{0;1\}}$ occurs (see Fig. 5b) whereas $(\tau)_{x=\{0;W/H\}}$ decreases.



Fig. 5. For various values of H_0 and W_0 , the relative mean shear stress: a) at the isothermal wall $\Gamma_T = \left(\frac{\tau}{\tau_{bf}}\right)_{x=0,0.25}$; b) at the adiabatic wall $\Gamma_Q = \left(\frac{\tau}{\tau_{bf}}\right)_{z=0,1}$. The values of H_0 for the thickness of the thermal and dynamic boundary layers, $\delta_{\theta}(z=0.5)$ and $\delta_w(z=0.5)$, are superimposed.

284 3.1.2. Heat transfer

The size effect of adiabatic rectangular obstacle on the heat transfer is now studied in 285 detail. In Figure 6, the evolution of the relative gain of heat transfer G_{Nu} is shown for various 286 values of the vertical and horizontal gaps, H_0 and W_0 , respectively. For $H_0 \ge 0.15$, whatever 287 the value of W_0 , a small value of the relative heat transfer gain $\langle G_{\rm Nu} \rangle$ is obtained, less than 288 1%. As H_0 decreases to $\delta_w(z=0.5)$, the heat transfer is higher than 1%; $\langle G_{\rm Nu} \rangle$ increases 289 continuously and reaches a local maximum for all W_0 . If the separation between the adiabatic 290 wall and the obstacle is narrowed, $H_0 < \delta_w(z = 0.5), \langle G_{\rm Nu} \rangle$ diminishes continuously probably 291 because of the friction. It can also be noted that if $W_0 = \delta_{\theta}(z = 0.5) = 0.03$, the relative 292 gain is always negative, i.e. the heat transfer is less efficient than the base case whatever the 293 value of H_0 again probably due to the increase of the pressure lost. Finally, it can be noted 294 that the heat transfer is maximum, $\langle G_{\rm Nu} \rangle = 2.6\%$, for $H_0 = 0.05$ and $W_0 = 0.04$. This case 295 is called from this point the best rectangular case. 296



Fig. 6. For various values of H_0 and W_0 , the relative gain of heat transfer $\langle G_{\text{Nu}} \rangle$. Values of H_0 for the thickness of the thermal and dynamic boundary layers, $\delta_{\theta}(z=0.5)$ and $\delta_w(z=0.5)$, is superimposed.

In Figure 7, for a fixed $W_0 = 0.04$ and three values of H_0 , profiles of Nusselt number 297 $Nu(W_0 = 0.04, H_0)$ along the hot wall are shown. The base case is also presented for 298 comparison. It can be observed that when a small rectangular obstacle ($H_0 = 0.25$) is 299 introduced into the core of the cavity, the heat transfer behaviour is only slightly modified, 300 whatever the elevation z considered. In this case, the profile of the Nusselt number is close 301 to that of the base case and the global maximum of Nusselt number is near the bottom of the 302 cavity (z = 0.01). If the distance H_0 is decreased by 2.5 times $(H_0 = 0.10)$, the modifications 303 are more noticeable. Indeed, a global maximum is always present near the adiabatic wall 304 of the cavity but a local maximum appears at the height z = 0.1 which corresponds to the 305 bottom of the rectangular obstacle. For $z \ge 0.05$ and $z \le 0.25$, $Nu_{base} < Nu(H_0 = 0.1, W_0 =$ 306 0.04). For $z \ge 0.25$, Nu($H_0 = 0.1, W_0 = 0.04$) is slightly lower than the base case. Finally, 307 if the space between the obstacle and the adiabatic wall of the cavity is 2 times smaller (i.e. 308 $H_0 = 0.05$), the heat transfer is highly increased for 0.025 < z < 0.25, compared to the base 309 case. In particular, a higher global maximum of Nu is observed in comparison with the other 310 cases at the height $z = H_0 = 0.05$. 311



Fig. 7. Profiles of Nusselt number along the hot wall for various values of H_0 when $W_0 = 0.04$. The base case is also presented for comparison.

To evaluate more thoroughly the efficiency of heat transfer along the isothermal wall, a local comparison of the Nusselt numbers is presented in Table 2 for the different separations H_0 . The isothermal wall is divided in two parts: upstream $z \leq 0.25$ and downstream z > 0.25. It appears clearly that the global enhancement of heat transfer is due to its increase in the upstream section (see $\langle G_{\rm Nu} \rangle (z \leq 0.25)$ in Tab. 2). So, the main goal of this work has been achieved.

318 3.2. Generation of new secondary flows induced by a backward-facing step (case (c) in Fig. 1)

In this section, the best geometry of the rectangular case is modified by a subsequent extrusion process. The main objective is to generate new secondary recirculations downstream

Table 2

H_0	$\langle G_{\rm Nu} \rangle (z \le 0.25)$	$\langle G_{\rm Nu} \rangle (z > 0.25)$	$\langle G_{\rm Nu} \rangle (0 \le z \le 1)$
0.25	+0.61%	-0.22%	+0.39%
0.20	+1.09%	-0.64%	+0.45%
0.15	+2.05%	-1.20%	+0.85%
0.10	+3.53%	-2.08%	+1.44%
0.05	+6.92%	-4.30%	+2.62%
0.03	+9.09%	-9.77%	-0.68%

For various H_0 , the relative gain of heat transfer $\langle G_{Nu} \rangle(z)$ in the upstream $(z \leq 0.25)$ and downstream (z > 0.25) parts when W_0 is fixed to 0.04.

the hot and cold boundary layers by a cut rectangular obstacle as those observed in the 321 previous work of [15] who used a local thermal perturbation to obtain them. To obtain the 322 optimal extrusion, two steps are considered. Firstly, the spacing H_0 and W_0 are fixed while 323 the distances H_1 (distance between the cavity adiabatic wall and the horizontal obstacle 324 surface) and W_1 (horizontal obstacle width after extrusion) are varied (see Figure 1c). In 325 a second step, starting from the best geometry which allowed to obtain the highest heat 326 transfer in the first step (called Extrusion 1), the distances obtained previously H_1 and W_1 327 are fixed whereas H_0 and W_0 are varied again. At the end of step two, the most favourable 328 case to the heat transfer is called: Extrusion 2. In following parts, velocity and temperature 329 fields are successively presented. 330

331 3.2.1. Flow dynamics

In Figure 8, steady flow visualizations using the LIC-method are shown for two extruded 332 obstacles and the best rectangle case determined previously. To compare with the best 333 excited case obtained by a localised time varying thermal perturbations at hot and cold 334 walls, the Fig. 8a presenting results from Thiers et al. [15] (see Fig. 8-E) is added. Indeed, 335 for the same Rayleigh number, the authors shown that an efficient way to enhance the heat 336 transfer is to disturb the hot wall at z = 0.7 and the cold wall at z = 0.3 using synchronised 337 local square waves of amplitude $\varepsilon = 1$ and frequency f = 0.403. At this thermal disturbance 338 position, the relative gain of global heat transfer by both disturbances is $\langle G_{\rm Nu} \rangle = 5.5\%$ [15]. 339 In Fig. 8a it can be observed that a large and unique recirculation zone is formed. Moreover, 340 the horizontal boundary layer along the adiabatic wall are thicker than those for the base 341 flow (see Fig. 3a). To take advantage of the modification of the downstream boundary layer 342 and the recirculation zone, the best rectangle is extruded gradually (see Fig. 8b). Figure 343 8c shows that when a small extrusion is created a small recirculation is formed (see point 344 A). On the contrary in Fig. 8d, the horizontal flow is divided in two parts when it impacts 345 the vertical obstacle tip (z = 0.95 or z = 0.05): the upper part of the flow is going to the 346 isothermal wall whereas the lower part follows the recirculation zone and is coming back to 347 the isothermal wall (see the red streamline in Fig. 8d). As a consequence, a stagnant zone 348 close to the obstacle (see the zone between the recirculation A and the obstacle). Thus in Fig. 349

³⁵⁰ 8d, the flow behaviour is closer to the flow when two thermal disturbances are simultaneously

introduced at the active walls (see Fig. 8a). Therefore it may be expected a higher heat

351

transfer comparatively with our best rectangular case.



Fig. 8. Line Integral Convolution (LIC) visualisation: a) best excited case by a local thermal perturbation (see previous work [15]) and three obstacles where $H_0 = 0.05$, $W_0 = 0.04$: b) The best rectangular case; c) obstacle 2: $H_1 = 0.1$, $W_1 = 0.085$; d) obstacle 1: $H_1 = 0.3$, $W_1 = 0.005$.

In Figure 9, flows are detailed in a more quantitative way. The best excited case is 353 not more taken into account. Vertical velocity profiles along the hot wall for the base 354 case, the best rectangular case, the case called Extrusion 1 and the case called Extrusion 355 2 are compared for six different heights $z \in \{0.05; 0.1; 0.5; 0.7; 0.8; 0.9\}$. For each case, the 356 distances H_0 , W_0 , H_1 and W_1 are reported in Tab. 3. In the upstream section (z = 0.05 and 357 z = 0.1) and the downstream section (z = 0.9), it is clear that each obstacle increases the 358 velocity gradient and the maximum velocity compared to the base case (see Fig. 9a). The 359 fluid is forced to flow in the upstream section where the Nusselt number tends to be lower 360 (see Fig. 7). However at z = 0.5 the base case has a higher maximum velocity. It can be 361 explained by the fact that in the other cases wall friction has decreased the available energy 362 (see Fig. 9a). In the downstream section (z = 0.7, z = 0.8 and z = 0.9) it can be observed 363 that velocity profiles are higher for the obstacle cases than for base case on the border of the 364 boundary layer (x > 0.04). For the Extrusion 2 case, reducing W_0 , the vertical maximum 365 velocity is increased in the upstream section (see green line in Fig. 9a), more than two times 366 at the height z = 0.05. 367



Fig. 9. Vertical velocity profiles along the hot wall for six different heights: a) upstream section; b) downstream section. Comparison between the base case, the best rectangular case ($H_0 = 0.05$, $W_0 = 0.04$), the extruded obstacle 1 ($H_1 = 0.3$, $W_1 = 0.005$) and the extruded obstacle 2 ($H_0 = 0.035$, $W_0 = 0.035$).

Table 3

For the three obstacles, the relative gain of heat transfer $G_{Nu}(z)$ in the upstream ($z \le 0.25$) and downstream (z > 0.25) parts.

case	H_0	H_1	W_0	W_1	$\langle G_{Nu} \rangle (z \le 0.25)$	$\langle G_{Nu} \rangle (z > 0.25)$	$\langle G_{Nu} \rangle (0 \le z \le 1)$
Rectangular	0.05	-	0.04	-	+6.92%	-4.30%	+2.62%
Extrusion 1	0.05	0.3	0.04	0.005	+7.04%	-3.37%	+3.67%
Extrusion 2	0.035	0.3	0.035	0.005	+18.00%	-13.61%	+4.39%

368 3.2.2. Heat transfer

The relative gain of heat transfer $\langle G_{\rm Nu} \rangle$ is plotted for various values of H_1 and W_1 in Fig. 369 10a. The distances H_0 and W_0 are maintained constant: $H_0 = 0.05$ and $W_0 = 0.04$. Clearly, 370 all simulated geometries generate a better heat transfer than the rectangular obstacle (which 371 has higher heat transfer than the base case). It can also be observed that there is a local 372 maximum of $\langle G_{\rm Nu} \rangle$ for each W_1 value. This local maximum increases as W_1 diminishes 373 until it reaches a global maximum value for $W_1 \rightarrow 0$ and $H_1 = 0.25$. In this study, for a 374 experimental consideration, the smallest thickness considered is $W_1 = 0.005$, which is 2% of 375 the total obstacle width. Thus, the best extruded case, called Extrusion 1, corresponds to a 376 relative gain $\langle G_{\rm Nu} \rangle = +3.67\%$. 377

The size of the obstacle which allows the highest heat transfer $(H_1 = 0.3)$ and $(W_1 = 0.005)$ are now fixed whereas H_0 and W_0 are varied again. In Fig. 10b, the relative gain of heat transfer $\langle G_{\text{Nu}} \rangle$ for various values of H_0 and W_0 is shown. The G_{Nu} value of Extrusion 1 is also presented for comparison (red dashed line). From $W_0 = H_0 = 0.05$, both values decrease until 0.03. It means that a compression of the vertical and horizontal boundary layers occurs. It can be observed that the best tested case, corresponding to $\langle G_{\rm Nu} \rangle = +4.39\%$, is obtained for $W_0 = H_0 = 0.035$. This case is called Extrusion 2.



Fig. 10. For two geometries, the relative gain of heat transfer $\langle G_{Nu} \rangle$: a) for various values of H_1 and W_1 when $H_0 = 0.05$ and $W_0 = 0.04$; b) for various values of H_0 and W_0 when $H_1 = 0.3$, $W_1 = 0.005$. The $\langle G_{Nu} \rangle$ value of the best rectangular geometry and best extrusion 1 are also presented for comparison (red dashed lines).

In the Figure 11, the vertical evolution of the relative gain of heat transfer, $G_{\rm Nu}(z)$, along 385 the hot wall are presented for the rectangular case, Extrusion 1 and Extrusion 2. Clearly, for 386 the upstream area $z \in [0; 0.25]$, the three obstacles increase the global heat transfer: +6.92%387 for the rectangular case, +7.04% for Extrusion 1 and +18% for Extrusion 2 (see Table 3). 388 Moreover, it can be observed that close to z = 0.05 the local gain reaches up to 80% for 389 the extrusion 2. However, the local heat transfer is reduced, $G_{\rm Nu}(z) < 0$ for both extrusions 390 when $z \in [0.25; 1]$ and for $z \in [0.25; 0.9]$ in the rectangular case. This is due to the fact 391 that more cold air is in contact with the hot plate, leading to an increase of heat transfer 392 in the upstream part $(z \in [0; 0.25])$; but as a consequence, the ascent of more hot air along 393 the hot plate provokes a decrease of heat transfer in the downstream part $z \in [0.25; 0.9]$. 394 For the rectangular case, when $z \in [0.9; 1]$, the gain is again positive, up to 10%. Finally, 395 at the height z = 0.7, it can be observed that the sudden widening diminishes the gain for 396 the extrusion 2 case contrary to the rectangular case (see the change of the slope of the red 397 curve). 398

399 3.3. Effects of the thermal conductivity

As it can be noticed experimentally, solids are not exactly adiabatic bodies, effects of fluid and solid thermal conductivity on the heat transfer are studied by considering $k_r =$ 10^{-3} , 1.0 and 10^2 (where k_r is the ratio of solid thermal conductivity k_s to the fluid thermal conductivity k_f : $k_r = k_s/k_f$). In Table 4, the relative gain of heat transfer $\langle G_{\rm Nu} \rangle$ is reported for the three solid obstacles. For $k_s = 10^{-3}$, that is to say for a weakly conductive solid, all values of $\langle G_{\rm Nu} \rangle$ are equal or very close to those of the adiabatic case. However, for $k_r = 1$ and $k_r = 10^2$, it is clear that the conductive condition reduces the gain of heat transfer



Fig. 11. Vertical evolution of the relative gain of heat transfer, $G_{Nu}(z)$, along the hot wall for three obstacles: rectangular case, extrusion 1 and extrusion 2.

407 significantly. For $k_s = 1$, which represents a thermal conduction close to that of polystyrene,

the gain diminishes around 1% for all solid geometries.

Table 4

Effects of the geometry and thermal conductivity of the solid obstacle k_s on the relative gain of heat transfer.

k_s	k_r	$\langle G_{Nu} \rangle_{\rm rectangular}$	$\langle G_{Nu} \rangle_{\text{extrusion 1}}$	$\langle G_{Nu} \rangle_{\text{extrusion 2}}$
adiabatic	0	2.62%	3.67%	4.39%
weakly conductive	10^{-3}	2.62%	3.67%	4.38%
air-like	1	2.45%	3.54%	3.69%
highly conductive	10^{2}	-2.51%	1.15%	0.58%

409 4. Conclusion

This work report the 2D direct numerical simulations of an air flow in a differentially 410 heated cavity of aspect ratio 4, at a Rayleigh number of 9×10^7 chosen just below than the 411 first critical Rayleigh number $(Ra_c = 1.02 \times 10^8)$. In order to improve the heat transfer at 412 the beginning of the boundary layers at the isotherm walls, three kinds of obstacle are tested 413 looking for the optimum size: rectangular, and two cut rectangular forms. With an obstacle, 414 in the middle of the cavity, which compresses the dynamic boundary layer at the isotherm 415 wall, it is possible to enhance the heat transfer globally up to 4.39% compared to the heat 416 transfer in a cavity without obstacle, thanks to an extruded rectangle. This is due to the 417 increase of the velocity downstream the boundary layers at the isotherm walls. Locally, the 418 gain could be higher than 80%. Thus the main conclusion of this work is that the presence 419

of an adiabatic obstacle increases the heat transfer in the cavity by a passive way. We finally
verify that a conductive obstacle does not improve the heat transfer as an adiabatic one
does. On the contrary, as the thermal conductivity of the obstacle increases, the global heat
transfer decreases. It has to be noted that this study is valid for any Rayleigh number below
the first critical Rayleigh number.

The next step of this work is a generalization to a 3D cavity in order to study how the obstacle control the interactions between 3D flow structures and the heat transfer, for laminar and turbulent flows.

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